

Fluid dynamics in Computer Animation

Roman Berka

KPGI

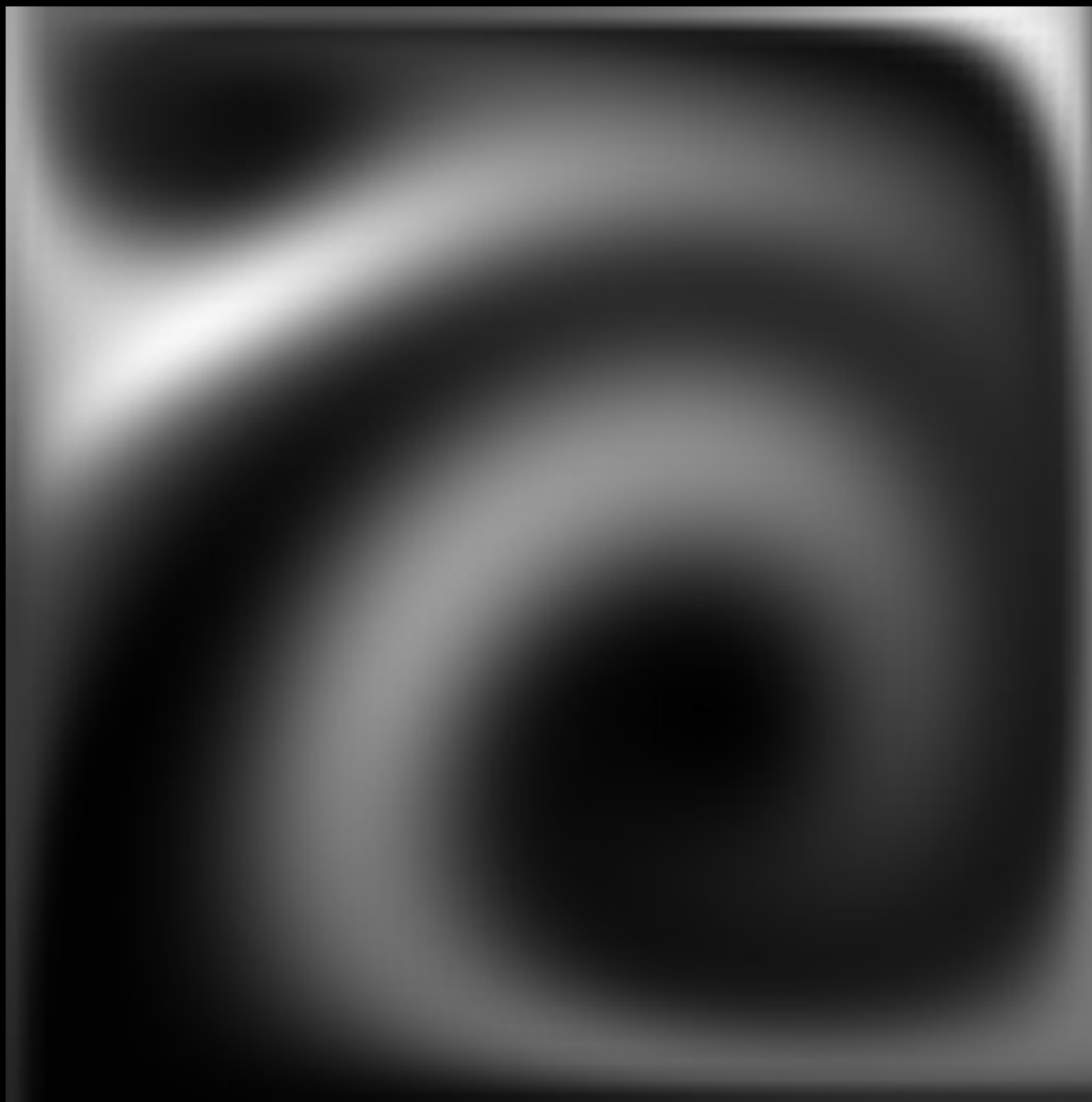
Talk overview

- **FD: field of application**
- **physical & math background**
- **methods**
- **examples**

Applications of FD

- **Smoke**
- **Water**
- **Fire**
- **Viscous Fluids**







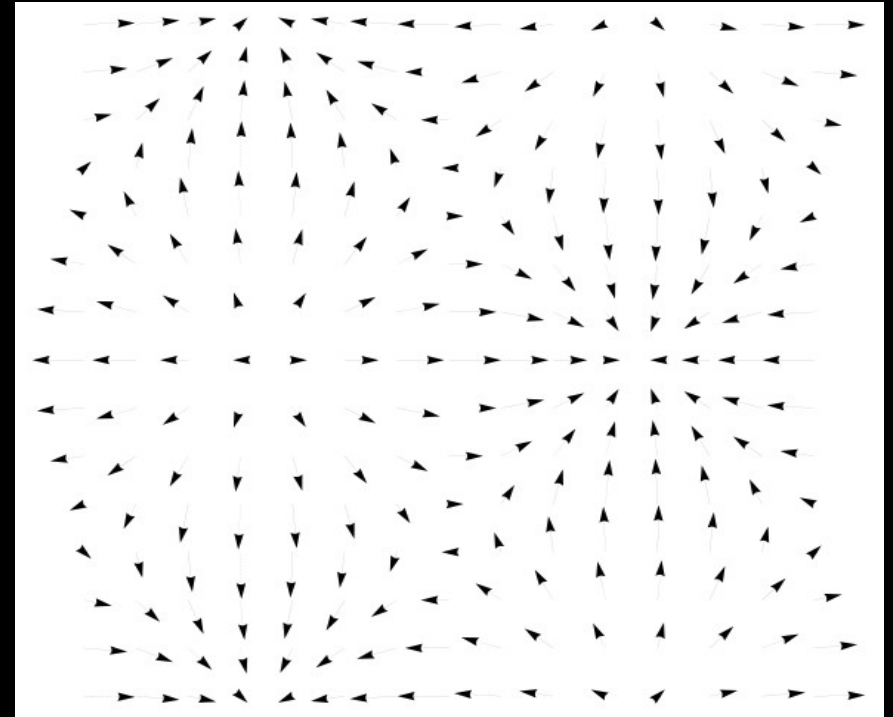
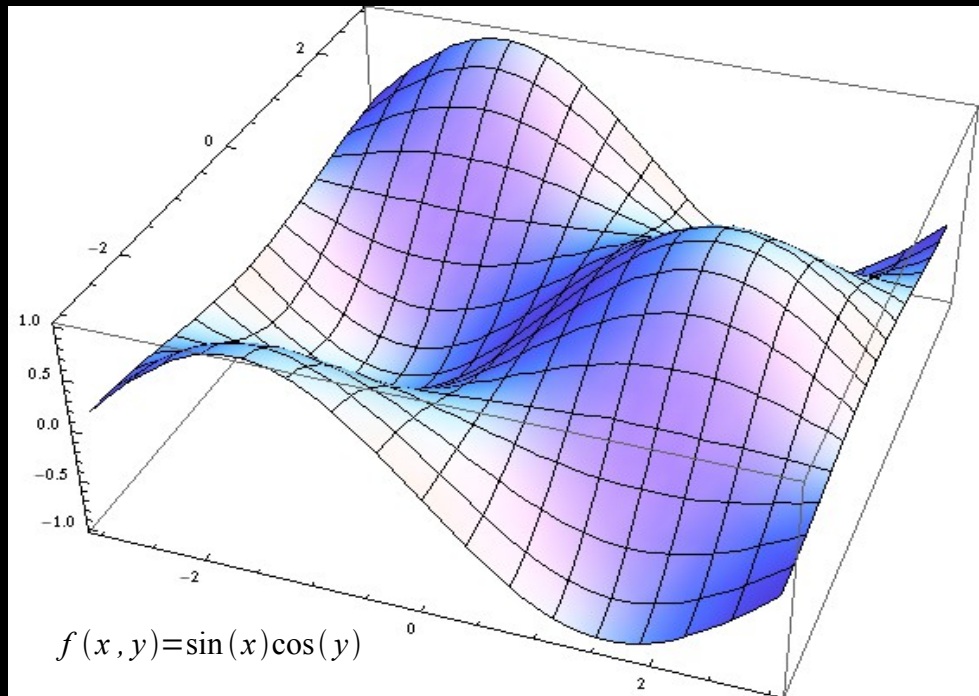
Math Phys background

scalar field $f(x, y, z) \rightarrow \mathbb{R}$

gradient $\nabla = (\frac{\partial}{\partial x}, \frac{\partial}{\partial y}, \frac{\partial}{\partial z})$

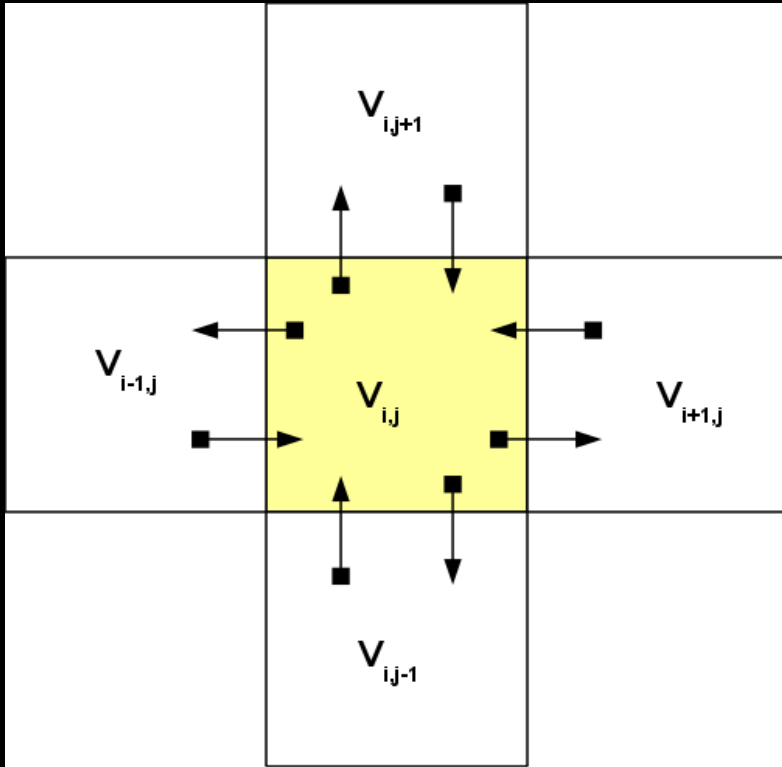
$$\nabla f = (\frac{\partial f}{\partial x}, \frac{\partial f}{\partial y}, \frac{\partial f}{\partial z}) = \text{grad } f$$

Math & Phys Background



$$\mathbf{F} = \nabla f$$

Math & Phys Background



Divergence

$$\nabla \cdot F = \text{Div } F$$

$$\nabla \cdot \mathbf{u} = \nabla \cdot (u, v, w) = \frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} + \frac{\partial w}{\partial z}$$

a measure of a flow through any
infinitesimal volume dV surrounding
a given point

Math & Phys Background

Curl

$$\nabla \times \mathbf{u} = \nabla \times (u, v, w) = \left(\frac{\partial w}{\partial y} - \frac{\partial v}{\partial z}, \frac{\partial u}{\partial z} - \frac{\partial w}{\partial x}, \frac{\partial v}{\partial x} - \frac{\partial u}{\partial y} \right)$$

a measure of how vector field rotates around any point

Laplacian

$$\nabla \cdot \nabla f = \nabla^2 f = \frac{\partial^2 f}{\partial x^2} + \frac{\partial^2 f}{\partial y^2} + \frac{\partial^2 f}{\partial z^2}$$

Physical Description of Fluids

Physics of FD: Euler, Navier, Stokes 1750-1850

Navier-Stokes Equations:

$$\nabla \cdot \mathbf{u} = 0$$

$$\frac{\partial \mathbf{u}}{\partial t} = -(\mathbf{u} \cdot \nabla) \mathbf{u} - \frac{1}{\rho} \nabla p + \nu \nabla^2 \mathbf{u} + \mathbf{f}$$

1950 > use of computers > numerical solutions

equations express the law of mass and momentum conservation

Density & Vector Fields

A Stable solver by Jos Stam

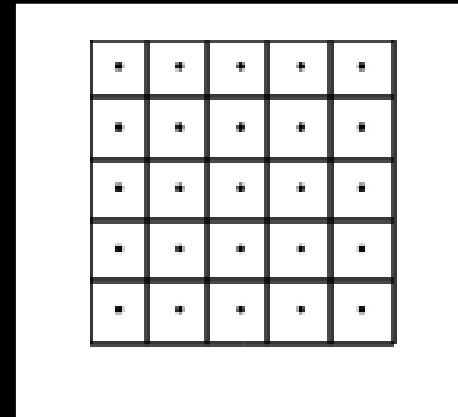
$$\frac{\partial \rho}{\partial t} = -(\mathbf{u} \cdot \nabla) \rho + \kappa \nabla^2 \rho + S$$

$$\frac{\partial \mathbf{u}}{\partial t} = -(\mathbf{u} \cdot \nabla) \mathbf{u} + \nu \nabla^2 \mathbf{u} + \mathbf{f}$$

...solution is splitted into two parts given by contributions of density field and velocity field

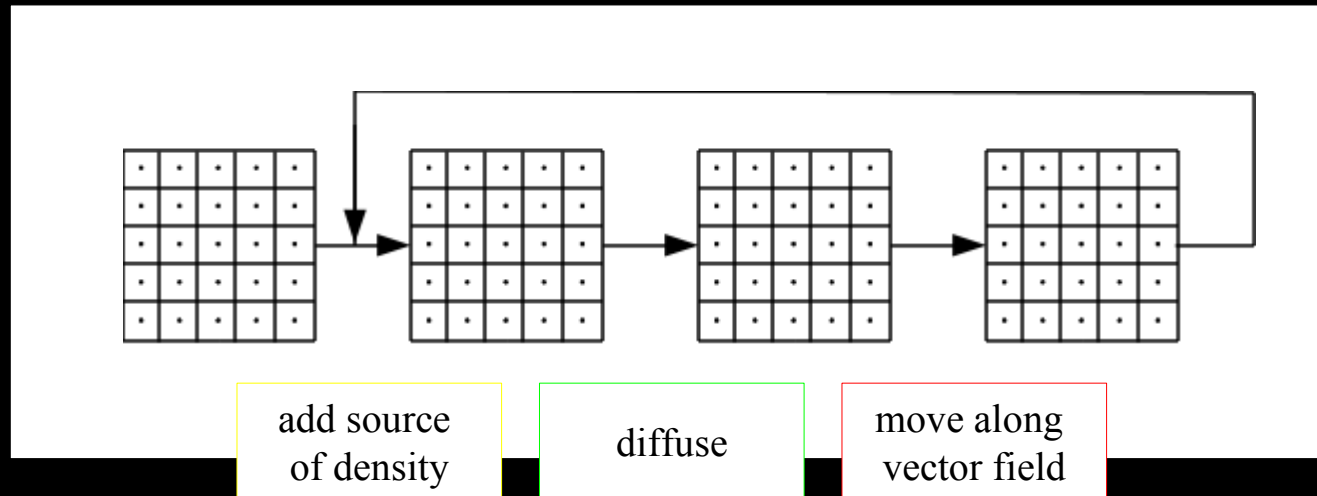
Solution Overview

```
Do {  
    Get Force  
    Get Density Source  
    Update Velocity  
    Update Density  
    Display Density  
} until simulation is in progress
```



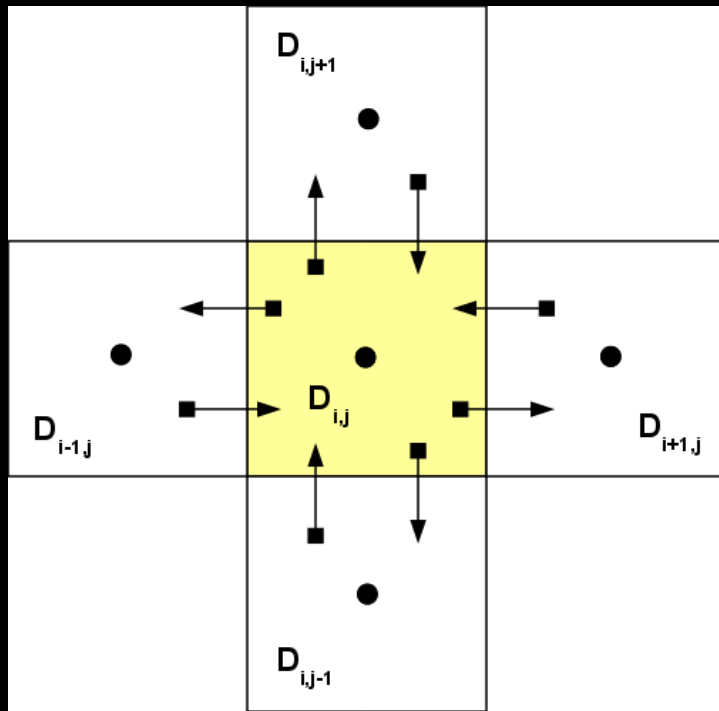
space subdivision

Density solver



$$\frac{\partial \rho}{\partial t} = -(\mathbf{u} \cdot \nabla) \rho + \kappa \nabla^2 \rho + S$$

Diffusing the Density



diffusion on single border is given as difference of densities:

$$Diff = \kappa dt (P_{neighbor} - P_{center}) \frac{1}{h^2}, h = \frac{1}{N}$$

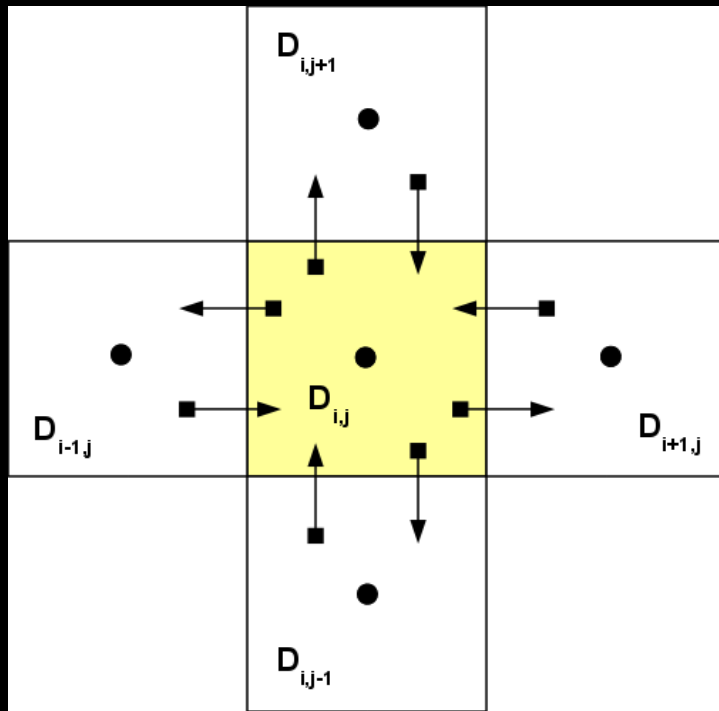
sum over all borders:

$$D_{i,j}^{n+1} = D_{i,j}^n + \kappa dt (D_{i-1,j}^n + D_{i+1,j}^n + D_{i,j-1}^n + D_{i,j+1}^n - 4D_{i,j}^n) \frac{1}{h^2}$$

unstable!!! :-(

Diffusing the Density

Backtracking the density in the time.



reversion of update rule:

$$D_{i,j}^n = D_{i,j}^{n+1} - \kappa dt (D_{i-1,j}^{n+1} + D_{i+1,j}^{n+1} + D_{i,j-1}^{n+1} + D_{i,j+1}^{n+1} - 4D_{i,j}^{n+1}) \frac{1}{h^2}$$

Solving system of linear equations:

$$b = Ax$$

...a linear solver necessary (e.g. Gaussian relaxation)

Moving densities

$$\frac{\partial \rho}{\partial t} = -(\mathbf{u} \cdot \nabla) \rho + \kappa \nabla^2 \rho + S$$

Looking for the stable solution...

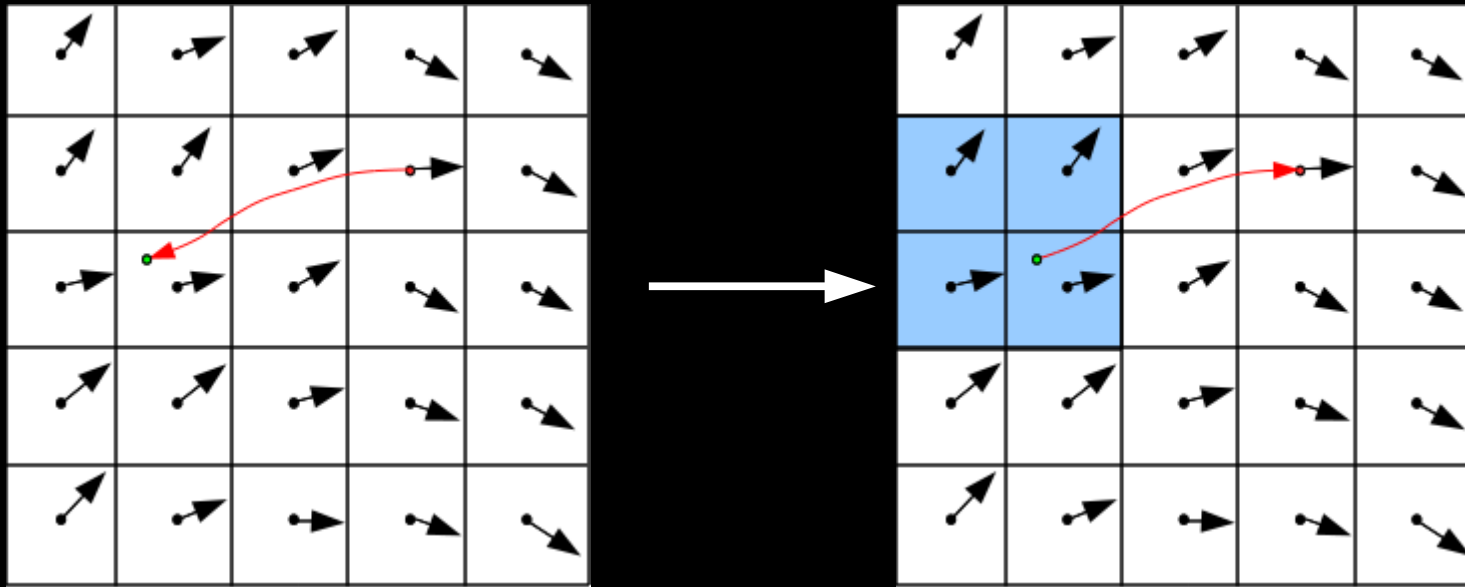
stability condition:

$$\Delta t |\mathbf{u}| < h$$

Moving Densities

Solving a system of linear equations is impossible...

Backtracking particles inside grid



Update of new value interpolating values
of the nearest neighbors

Computing Velocity Field

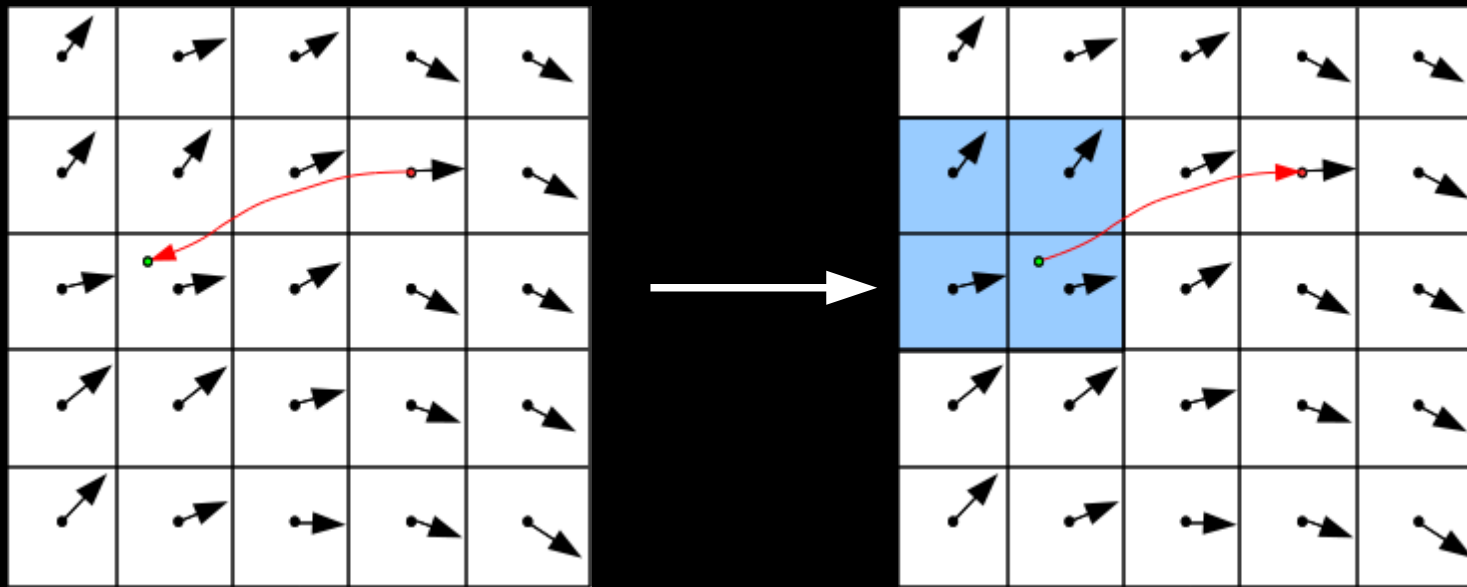
$$\frac{\partial \mathbf{u}}{\partial t} = -(\mathbf{u} \cdot \nabla) \mathbf{u} + \nu \nabla^2 \mathbf{u} + \mathbf{f}$$



HLÍDEJTE SI TY VZÁCNÉ OKAMŽIKY, KDY VÁM TO JEŠTĚ MYSLÍ. MOHOU BÝT POSLEDNÍ.

Moving the Velocity Field

Backtracking the particle's velocity as for density before...



Conserving Mass

$$\nabla \cdot \boldsymbol{u} = 0$$

Helmholtz-Hodge Decomposition:

$$\boldsymbol{w} = \boldsymbol{u} + \nabla q$$

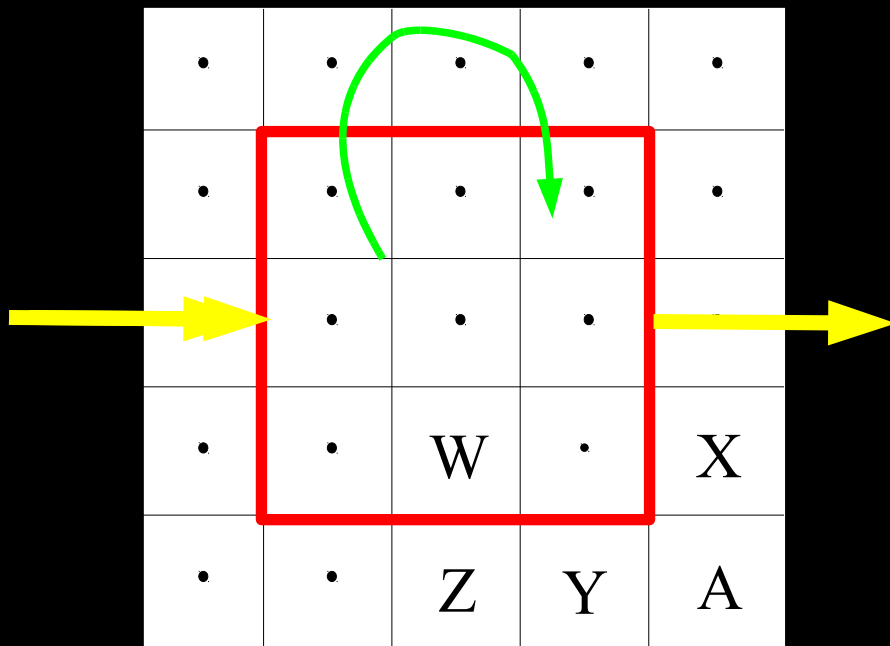
$$\boldsymbol{u} = \boldsymbol{w} - \nabla q$$

$$\nabla \cdot \boldsymbol{w} - \nabla \cdot \nabla q = 0$$

$$\nabla \cdot \boldsymbol{w} - \nabla^2 q = 0$$

Boundary Conditions

simulation inside a closed box
velocity is to be zero on boundaries or
velocity continues on the opposite wall or
... other boundary conditions are possible



$$A = (X+Y)/2$$

$$Z = -W \text{ for velocities}$$

$$Z = W \text{ for densities}$$

Example

references

- **Jos Stam, "Real-Time Fluid Dynamics for Games". Proceedings of the Game Developer Conference, March 2003.**
- **Jos Stam, "Stable Fluids", In SIGGRAPH 99 Conference Proceedings, Annual Conference Series, August 1999, 121-128.**